

# EU Data Act

## Data specifications submitted by WPBD products

September 12, 2025



Panasonic Connect Co., Ltd.  
Welding Process Business Division  
Development Department

**This document presents the data that WPBD products can provide to comply with EU Data Act.**

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Established / Revision history

Revision No.	Revision date	Revisions	Charge	Approval
0	September 12, 2025	First version is released.	Kitada	Yonemori

- Product Category : Welding power source
- Product Name : TIG Welding power source
- Product Number : YC-300BZ3YHD、 YC-300BP2YAF
- Requirements of Data Submission : TIG Welding power source has to be connected to a Panasonic Robot Controller.
- Data to be submitted : See the table below

	Data name	Unit	Number of bytes	Sampling Period (ms)
1	Output current	A	2	500
2	Output voltage	V	2	500
3	Welding error	—	3	Every time
4	Welding power source detection status	—	1	Every time

- Product Category : Welding power source
- Product Name : CO<sub>2</sub>/MAG/MIG Welding power source
- Product Number : YD-400VP1YHD
- Requirements of Data Submission : CO<sub>2</sub>/MAG/MIG Welding power source has to be connected to a Panasonic Robot Controller.
- Data to be submitted : See the table below

	Data name	Unit	Number of bytes	Sampling Period (ms)
1	Output current	A	2	500
2	Output voltage	V	2	500
3	Shot count	time	1	500
4	Motor current	A	1	500
5	Motor speed	rpm	2	500
6	Welding error	—	3	Every time
7	Welding power source detection status	—	1	Every time

- Product Category : Robot
- Product Name : G4 Controller
- Product Number : YA-2JA Series、YA-2KA Series
- Requirements of Data Submission : Various options have to be used.
- Data to be submitted : See the table below

	Option Name	Part number	Function name	Data name	Unit	Sampling period
1	TAWERS Weld Data	YA-2KPWY1	Weld data recording	Current output	A	50us
2	Management			Voltage output	V	
3				Wire speed	m/min	
4				Program name	-	50ms
5				Position name	-	
6				Error number	-	
7				Weld speed	m/min	
8				Command current	A	
9				Current output	A	
10				Command voltage	V	
11				Voltage output	V	
12				Shot count	time	
13				Pulse frequency	Hz	
14				Motor current	A	
15				Wire speed	m/min	
16				Instant arc-lack time	ms	
17			Weld data log	Program name	-	Each time a weld
18				Position name	-	
19				Command current	A	
20				Command Ip	A	
21				Command voltage	V	
22				Weld speed	m/min	
23				Current output	A	
24				Voltage output	V	
25				Shot count	time	
26				Instant arc-lack time	ms	
27				Motor current	A	
28				Wire speed	m/min	
29				Weld error	-	
30				Deviation count	time	

	Option Name	Part number	Function name	Data name	Unit	Sampling period
31	Welding Data Log (General Welder)	YA-2JPWY2T01	Weld data log	Program name	-	Each time a weld
32				Position name	-	
33				Command current	A	
34				Command voltage	V	
35				Command Ib	A	
36				Command Ip	V	
37				Weld speed	m/min	
38				Current output	A	
39				Voltage output	V	
40				Shot count	time	
41				Motor current	A	
42				Wire speed	m/min	
43				Weld error	-	
44				Deviation count	time	
45	Teaching Update Log	YA-2JPXC1	Teaching Update Log	-	-	For each change operation
46				Opening a file	-	
47				Saving a file with a new name	-	
48				Command add	-	
49				Command change	-	
50				Command delete	-	
51				Move command	-	
52				Undoing an operation	-	
53				Canceling an "UNDO" operation	-	

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	Option Name	Part number	Function name	Data name	Unit	Sampling period
54	Production Management Function	YA-2JPXD1	Auto Data Receiving	Accumulation	YY,MM,DD,hh,m m,ss	Every Request (min. 1 min)
55				Error history	-	
56				Alarm history	-	
57				Production count	Measurement section unit	
58				Operation time	YY,MM,DD,hh,m m,ss	
59			Welding information : Production evet log	Log start	YY,MM,DD,hh,m m,ss	Each time a weld
60				Work S/N	-	
61				Weld line ID	-	
62				Torch ON time	YY,MM,DD,hh,m m,ss	
63				Torch OFF time	YY,MM,DD,hh,m m,ss	
64				Program name	-	
65				Weld start position	-	
66				Log position	-	
67				Wire amount	m	
68				Arc retry count	time	
69				Stick release count	time	
70				Weld error	-	
71				Command current	A	
72				Command voltage	V	
73				Weld speed	m/min	
74				Current output	A	
75				Voltage output	V	
76				Shot count	time	
77				Total instant arc lack time	ms	
78				Feeder motor current	A	
79				Wire speed	m/min	
80				Arc monitor time	s	
81				Arc time	YY,MM,DD,hh,m m,ss	
82				MAG touch start	-	
83				Deviation counts	time	
84				Login User ID	-	
85				Multi-cooperative robot state	-	
86				Weld characteristics No.	-	
87				Weld characteristics	-	

	Option Name	Part number	Function name	Data name	Unit	Sampling period
88	Production Management Function	YA-2JPXD1	Operation information : Production evet log	Log start	YY,MM,DD,hh,m m,ss	Every Log Event
89				Serial No.	-	
90				Event type	-	
91				Program name	-	
92				Program start position	-	
93				Log position	-	
94				Error code	-	
95				Error sub code	-	
96				Average load factor	%	
97				Peak load factor	%	
98				Collision torque	%	
99				Any 10 variables	-	
100				Running Time	s	
101				Holding time in Auto mode	s	
102				Error hold time in Auto mode	s	
103				Servo OFF time in Auto mode	s	
104				Idle time in Auto mode	s	
105				Teaching time	s	
106				Controller power ON time	s	
107				Arc ON time in Auto mode	s	
108				Downtime (Error)	-	
109				Waiting time in Auto mode	s	
110				Air cut time in Auto mode	s	
111				Login User ID	-	
112	Robot Data Access Function	YA-2JPXE1	-	Robot position data/Each axis data/Work coordinate data/Load factor for each axis	-	Every acquisition : 10 ms minimum
113				External axis angle data/Load factor (1-21)	-	
114				Welding data (Set current, Actual current, Set voltage, Actual voltage, Wire speed, Feeder motor current)	-	
115				Welding data for follower robot (Set current, Set voltage, Tool number, etc)	-	
116				Status INPUT/OUTPUT data	-	
117				User INPUT/OUTPUT data	-	
118				GI variable (100 pcs.), GL variable (5 pcs.)	-	
119				Time data (Accumulated program execution time, Accumulated power ON time, etc.)	-	

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	Option Name	Part number	Function name	Data name	Unit	Sampling period
120	OPC UA server Function	YA-2JPXK1	OPC UA for Robotics	Login user name	-	Every acquisition
121				Manufacturer	-	
122				Model name	-	
123				Serial number	-	
124				Firmware information	-	
125				Operation program information	-	
126				Manipulator	-	
127				Manufacturer	-	
128				Model number of manipulator	-	
129				Robot type	-	
130				Axis information/	-	
131				Axis type	-	
132				ParameterSet/	-	
133				Angle and so on	-	
134				Safety information	-	
135				ParameterSet/	-	
136				Emergency stop state	-	
137				Operation mode	-	
138				Protective stop	-	

	Option Name	Part number	Function name	Data name	Unit	Sampling period
139	Thick Plate Welding Function	YA-2JPMB1/C1	Thick Plate Event Log	File operation information (File Reset, Transfer, File Open/Close)	-	Every request
140				Operation information (start, restart, stop, direct go, etc.)	-	
141				Error code	-	
142			Welding Condition Setting File	Weld Information (Multi-layer welding starts, Multi-layer pass shift, Multi-layer welding ends, Weld starts, Weld ends, Weld condition number)	-	Every request
143				Weld start condition (current)	A	
144				Weld start condition (voltage)	V	
145				Weld start condition (speed)	m/min	
146				Weld start condition (timer)	s	
147				Weld end condition (weld confirmation timer)	s	
148				Weld end condition (Afterflow Timer)	s	
149				Start retry	-	
150				Operation after start (current)	A	
151				Operation after start (voltage)	V	
152				Operation after start (timer)	s	
153				Operation after start (speed)	m/min	
154				Joint (weaving pattern)	-	
155				Joint (amplitude)	m	
156				Joint (height)	m	
157				Arc sensor settings	なし	
158				Pass shift	m	
159				Weld end condition (current)	A	
160				Weld end condition (voltage)	V	
161				Weld end condition (speed)	m/min	
162				Start shift	m	
163	Touch Sensor Function	YA-2JPWS1	Touch Sensor File(SLS)	Sensor number table	-	Every request
164				Sensor movement commands	-	
165			TSF	Touch sensor correction data	mm	Every request

End

- Product Category : Robot
- Product Name : G3 Controller
- Product Number : YA-1V/YA-1Y/YA-2D/YA-2F/YA-1W/YA-1Z/YA-2E/YA-2G Series
- Requirements of Data Submission : Various options have to be used.
- Data to be submitted : See the table below

	Option Name	Part number	Function name	Data name	Unit	Sampling period
1	TAWERS Weld Data Management	YA-1TPWY2	Weld data recording	Current output	A	300us
2				Voltage output	V	
3				Wire speed	m/min	
4				Program name	-	50ms
5				Position name	-	
6				Error number	-	
7				Weld speed	m/min	
8				Command current	A	
9				Current output	A	
10				Command voltage	V	
11				Voltage output	V	
12				Shot count	time	
13				Pulse frequency	Hz	
14				Motor current	A	
15				Wire speed	m/min	
16				Instant arc-lack time	ms	Each time a weld
17			Weld data log	Program name	-	
18				Position name	-	
19				Command current	A	
20				Command Ip	A	
21				Command voltage	V	
22				Weld speed	m/min	
23				Current output	A	
24				Voltage output	V	
25				Shot count	time	
26				Instant arc-lack time	ms	
27				Motor current	A	
28				Wire speed	m/min	
29				Weld error	-	
30				Deviation count	time	

	Option Name	Part number	Function name	Data name	Unit	Sampling period
31	Welding Data Log (General Welder)	YA-1UPWY2T01	Weld data log	Program name	-	Each time a weld
32				Position name	-	
33				Command current	A	
34				Command Ip	A	
35				Command voltage	V	
36				Weld speed	m/min	
37				Current output	A	
38				Voltage output	V	
39				Shot count	time	
40				Instant arc-lack time	ms	
41				Motor current	A	
42				Wire speed	m/min	
43				Weld error	-	
44				Deviation count	time	
45	Teaching Update Log	YA-1UPXC1	Teaching Update Log	-	-	For each change operation
46				File	-	
47				Edit	-	
48				Program edit	-	
49				Mode switch	-	
50				Resume	-	
51				User login	-	

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	Option Name	Part number	Function name	Data name	Unit	Sampling period
52	Production Management Function	YA-1UPXD1	Auto Data Receiving	Accumulation	YY,MM,DD,hh,m m,ss	Every Request (min. 1 min)
53				Error history	なし	
54				Alarm history	なし	
55				Production count	Measurement section unit	
56				Operation time	YY,MM,DD,hh,m m,ss	
57	Welding information : Production evet log			Log start	YY,MM,DD,hh,m m,ss	Each time a weld
58				Work S/N	-	
59				Weld line ID	-	
60				Torch ON time	YY,MM,DD,hh,m m,ss	
61				Torch OFF time	YY,MM,DD,hh,m m,ss	
62				Program name	-	
63				Weld start position	-	
64				Log position	-	
65				Wire amount	m	
66				Arc retry count	time	
67				Stick release count	time	
68				Weld error	-	
69				Command current	A	
70				Command voltage	V	
71				Weld speed	m/min	
72				Current output	A	
73				Voltage output	V	
74				Shot count	time	
75				Total instant arc lack time	ms	
76				Feeder motor current	A	
77				Wire speed	m/min	
78				Arc monitor time	s	
79				Arc time	YY,MM,DD,hh,m m,ss	
80				MAG touch start	-	
81				Deviation counts	time	
82				Login User ID	-	
83				Multi-cooperative robot state	-	
84				Weld characteristics No.	-	
85				Weld characteristics	-	

	Option Name	Part number	Function name	Data name	Unit	Sampling period
86	Production Management Function	YA-1UPXD1	Operation information : Production evet log	Log start	YY,MM,DD,hh,m m,ss	Every Log Event
87				Serial No.	-	
88				Event type	-	
89				Program name	-	
90				Program start position	-	
91				Log position	-	
92				Error code	-	
93				Error sub code	-	
94				Average load factor	%	
95				Peak load factor	%	
96				Collision torque	%	
97				Any 10 variables	-	
98				Running Time	s	
99				Holding time in Auto mode	s	
100				Error hold time in Auto mode	s	
101				Servo OFF time in Auto mode	s	
102				Idle time in Auto mode	s	
103				Teaching time	s	
104				Controller power ON time	s	
105				Arc ON time in Auto mode	s	
106				Downtime (Error)	-	
107				Waiting time in Auto mode	s	
108				Air cut time in Auto mode	s	
109				Login User ID	-	
110	Robot Data Access Function	YA-1UPXE1	-	Robot position data/Each axis data/Work coordinate data/Load factor for each axis	-	Every acquisition : 10 ms minimum
111				External axis angle data/Load factor (1-21)	-	
112				Welding data (Set current, Actual current, Set voltage, Actual voltage, Wire speed, Feeder motor current)	-	
113				Welding data for follower robot (Set current, Set voltage, Tool number, etc)	-	
114				Status INPUT/OUTPUT data	-	
115				User INPUT/OUTPUT data	-	
116				GI variable (100 pcs.), GL variable (5 pcs.)	-	
117				Time data (Accumulated program execution time, Accumulated power ON time, etc.)	-	

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	Option Name	Part number	Function name	Data name	Unit	Sampling period
118	Thick Plate Welding Function	YA-1UPMB1/C1	Thick Plate Event Log	File operation information (File Reset, Transfer, File Open/Close)	-	Every request
119				Operation information (start, restart, stop, direct go, etc.)	-	
120				Error code	-	
121				Weld Information (Multi-layer welding starts, Multi-layer pass shift, Multi-layer welding ends, Weld starts, Weld ends, Weld condition number)	-	
122		Welding Condition Setting File		Weld start condition (current)	A	Every request
123				Weld start condition (voltage)	V	
124				Weld start condition (speed)	m/min	
125				Weld start condition (timer)	s	
126				Weld end condition (weld confirmation timer)	s	
127				Weld end condition (Afterflow Timer)	s	
128				Start retry	-	
129				Operation after start (current)	A	
130				Operation after start (voltage)	V	
131				Operation after start (timer)	s	
132				Operation after start (speed)	m/min	
133				Joint (weaving pattern)	-	
134				Joint (amplitude)	m	
135				Joint (height)	m	
136				Arc sensor settings	-	
137				Pass shift	m	
138				Weld end condition (current)	A	
139				Weld end condition (voltage)	V	
140				Weld end condition (speed)	m/min	
141				Start shift	m	
142	Touch Sensor Function	YA-1VPWS1	Touch Sensor File(SLS)	Sensor number table	-	Every request
143				Sensor movement commands	-	
144			TSF	Touch sensor correction data	mm	Every request

End

- Product Category : Laser
- Product Name : (For Cutting) Direct Diode Laser Oscillator
- Product Number : YL-F40CA1E00、YL-F40C02T05、YL-F60C02T05、YL-F40D02Y05
- Data to be submitted : See the table below      note) Some models contain unused data. Output of unused data is “0”.

	Data name	Unit
1	Log data No.	-
2	year, month, day	year, month, day
3	hour, minute, second	hour, minute, second
4	Alarm No.	-
5	Input signal	-
6	Output signal	-
7	Oscillator temperature	0.01°C
8	Oscillator humidity	0.01%
9	Oscillator power voltage	0.01V
10	Water block temperature (Oscillator cooling water temperature)	0.01°C
11	Power on time	0.1sec
12	Cumulative oscillation time	0.1sec
13	Cumulative operation time	sec
14	LD temperature	0.01°C
15	Blade temperature	0.01°C

	Data name	Unit
16	Blade humidity	0.01%
17	Blade laser power	W
18	Blade safety relay operating factor	-
19	Blade PD (Photo Diode) output voltage	0.01V
20	Combiner temperature	0.01°C
21	Combiner humidity	0.01%
22	Combiner laser power	W
23	Combiner safety relay status	-
24	Combiner PD (Photo Diode) output voltage	0.01V
25	Guide laser PD (Photo Diode) output voltage	mV
26	FOM PD (Photo Diode) output voltage	mV
27	Alarm detail bits	-
28	Oscillator water pressure (IN)	0.001MPa
29	Oscillator water differential pressure (IN)	0.001MPa
30	Oscillator water flow rate	0.1L/min

- Product Category : Laser
- Product Name : LAPRISS
- Product Number, Oscillator : YL-F40AA\*、 Robot System : YA-1VS\*
- Requirements of Data Submission : It is as follows.
  - Use of the extra option (robot data access function)
  - Connecting G3 controller and external device such as PLC via LAN line
  - Development of data acquisition program using Modbus/TCP on external device
  - The robot data update cycle is every 1200 ms for The Blade related data and every 100 ms for other data.
  - The data acquisition cycle relies and is controlled by the external device.
- Data to be submitted : See the table below

	Address	Data name	Unit
1	8500	Laser status	-
2	8501	Laser command condition: Main (peak) power	W
3	8502	Laser command condition: Base power	W
4	8503	Laser command condition: Pulse frequency	Hz
5	8504	Pulse width (Duty)	x100 value [%]
6	8505	Welding speed	0.01m/min
7	8506	Start output factor	0~250%
8	8507	End output factor	0~250%
9	8508	ACC_stdrt_up Start-up slope time	0.0~5999.9ms
10	8509	DCC_end_down End down slope time	0.0~5999.9ms
11	8510	ACC_cond_up Condition up slope time	0.0~5999.9ms
12	8511	DCC_cond_down Condition down slope time	0.0~5999.9ms
13	8512	Speed	0.01m/min
14	8513	Primary supply voltage	0.01V
15	8514	Water pipe temperature	0.01°C

	Address	Data name	Unit
16	8515	Internal temperature	0.01°C
17	8516	Internal humidity	0.01%RH
18	8517	Water pipe dew point temperature	0.01°C
19	8518	In-machine dew point temperature	0.01°C
20	8519	Water pressure (IN)	0.001MPa
21	8520	Differential pressure	0.001MPa
22	8521	Flow rate	0.1L/min
23	8522	Combiner Laser output	W
24	8523	Combiner Safety relay	-
25	8524	Combiner_Temperature	0.01°C
26	8525	Combiner_Relative humidity	0.01%RH
27	8526	Combiner_Dew point temperature	0.01°C
28	8527	Combiner_FOM PD	mV
29	8528	Combiner_FOM PD Low	mV
30	8529	Combiner_FOM PD High	mV

	Address	Data name	Unit
31	8530	Blade1_Laser output	W
32	8531	Blade1_Safety relay	-
33	8532	Blade1_Temperature/LD temperature1	0.01°C
34	8533	Blade1_LD temperature2	0.01°C
35	8534	Blade1_Ambient temperature	0.01°C
36	8535	Blade1_Relative humidity	0.01%RH
37	8536	Blade1_Dew point temperature	0.01°C
38	8590	Beam switch_safety relay	-
39	8591	Beam switch_FOM PD CH1	mV
40	8592	Beam switch_FOM PD CH1 Low	mV
41	8593	Beam switch_FOM PD CH1 High	mV
42	8594	Beam switch_FOM PD CH2	mV
43	8595	Beam switch_FOM PD CH2 Low	mV
44	8596	Beam switch_FOM PD CH2 High	mV



**Panasonic**  
**CONNECT**

The image features the Panasonic CONNECT logo centered on a dark blue background. The word "Panasonic" is in white, and "CONNECT" is in a light blue color. The background includes a grid of squares and a large, semi-transparent blue circle on the left side.